



SAF Technology Increases Efficiency of Robotic Post- Processing Systems



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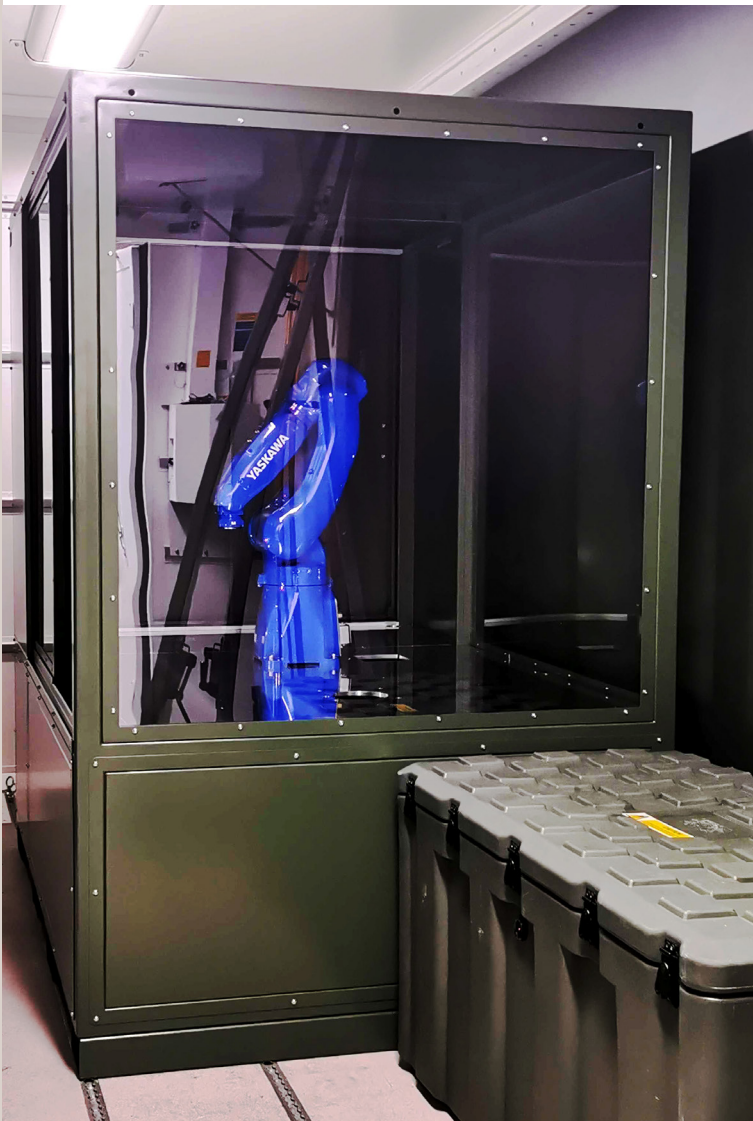
Robert Bush
CEO of Rivelin Robotics

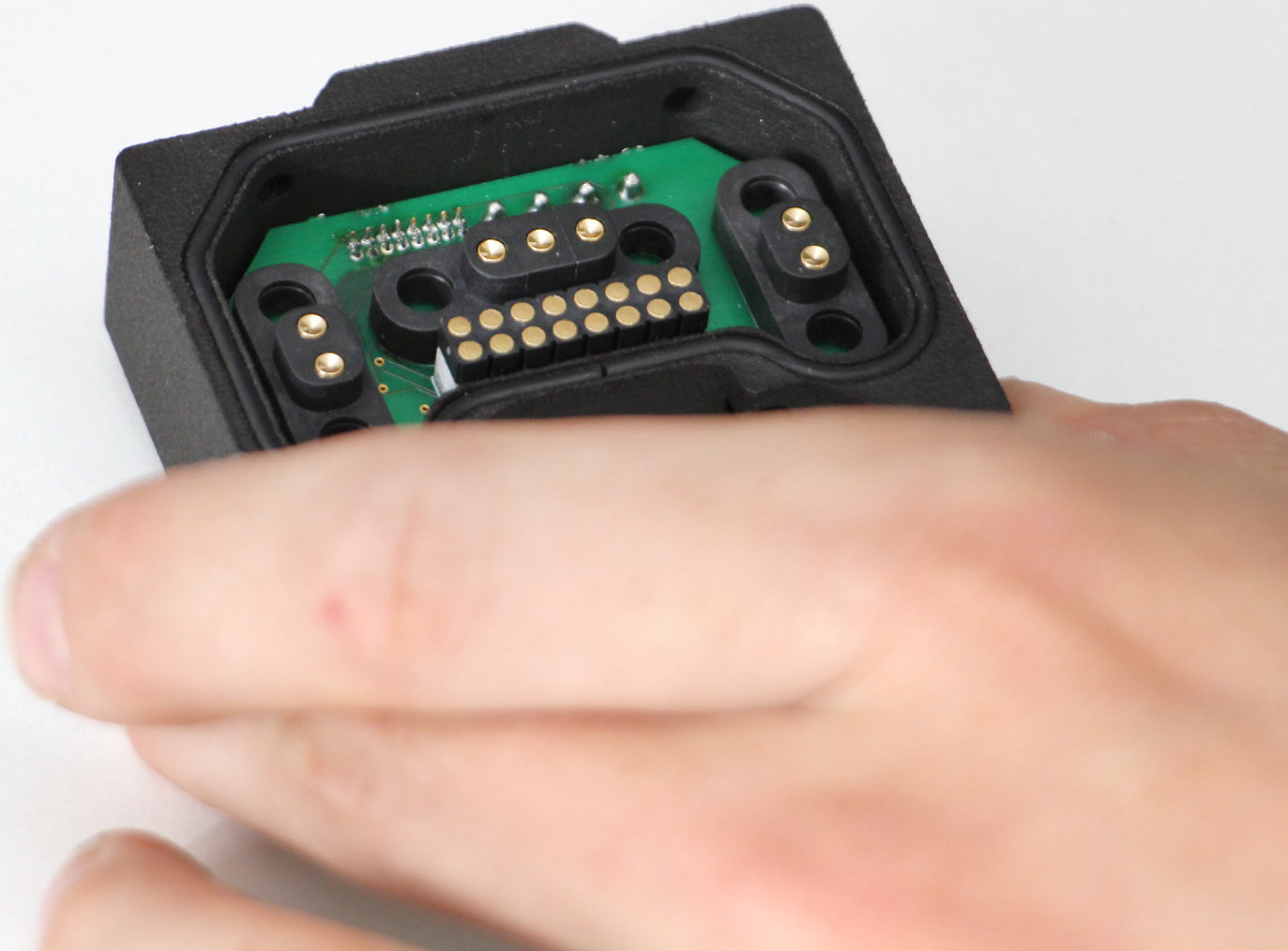


Based out of Sheffield, England, Rivelin Robotics specializes in metal additive manufacturing (AM) support removal and finishing. Specifically, the Rivelin Netshape® robots simplify, automate, and expedite post-processing in near-net-shape metal manufacturing.



According to Robert Bush, CEO of Rivelin Robotics: “At Rivelin we are developing solutions for post-processing metal AM parts. When off-the-shelf electrical components were not available to meet our needs, the talent and drive of the Rivelin team were deployed to develop an electrical connector that would. The SAF AM process and the materials it can utilize were a great match for our application both in terms of product development and production. It allowed us to prototype, test, and iterate quickly so that we were fully confident in our product and how it would perform.”





The missing link

Post-processing can pose a significant challenge as parts often have complex geometries. To overcome this, a variety of tools are required. To enable the use of multiple tools on a single robot arm, a tool changer is used on the end of the robot. Although the robot is small in size, the tools have higher than usual electrical demands, both in terms of current and total pin count. Based on these specifications, Rivelin Robotics struggled to find an off-the-shelf solution that could address both needs.

Connector iterations

With this in mind, Rivelin Robotics was determined to produce the solution they required and designed their first version of the electrical connector. Originally printed with a low-end FFF system, the connector worked well for a period of time. Unfortunately, the connector's design required extra sealing to improve its IP rating. It also required an upgrade for additional current carrying capacity. Finally, this first design was difficult to maintain.

Without a working connector, Rivelin's robots could no longer run. This delayed customers and Rivelin couldn't further their technology or designs. To address this issue, a new connector was required which was both easier to use and manufacture.

The solution

With the design freedom afforded by powder bed-based polymer processes, Rivelin Robotics landed on the H350™ 3D printer utilizing SAF technology. The second version of the connector, printed with SAF technology, offers a more modular and flexible approach. This connector is an electrical “plug” which enables the tool changer connector to pass data and power to the tool on the other end.

Designing and printing the connector

To perfect the connector, rapid prototyping was performed. This resulted in three separate batches with four complete sets for the robot and 50 sets for the tools. The build consisted of 360 parts, printed in only 12 hours. The connector was printed with SAF PA12 which creates precise and stiff parts.



Benefits and properties of the connector

This second version of the connector includes a separate, flexible, and integrated strain relief for the cable as the robot moves. This complex geometry was printed directly onto the connector body in a single piece utilizing SAF technology.



It is vital that the connector can be utilized on various tools and withstand high currents. Each high current power pin can take up to ten amps. The lower current data pins are able to reliably pass an amp each.

This is possible thanks to SAF technology's ability to manufacture tight tolerances. Each data pin is aligned correctly as individual pins are each inserted through a small hole. This intricacy reinforces a robust electrical connection. Dimensional repeatability is also key, with multiple sets of connectors being printed in the same build. SAF is able to provide interchangeable parts, ensuring that the pins on the two halves of the connector always fit together regardless of where they are printed.

Epoxy potting compound is added to the connector after assembly, making it completely waterproof. This further protects the robot's systems and enables the connector to resist any dust exposure.



Although both High Yield PA11 and PA12 are suitable for connectors, SAF™ PA12 was applicable in this specific instance as it exhibits improved stiffness and accuracy. In comparison, PA11 has excellent impact toughness and ductility for applications that experience more dynamic loads.

In the previous version of the connector, it was difficult to achieve thin walls. The O-ring groove sizing was also a challenge since the rings became slightly over-compressed. The SAF version enables a tight fit of connector housings, ensuring that the O-ring seals are perfectly aligned to maintain the IP rating of the assembly.

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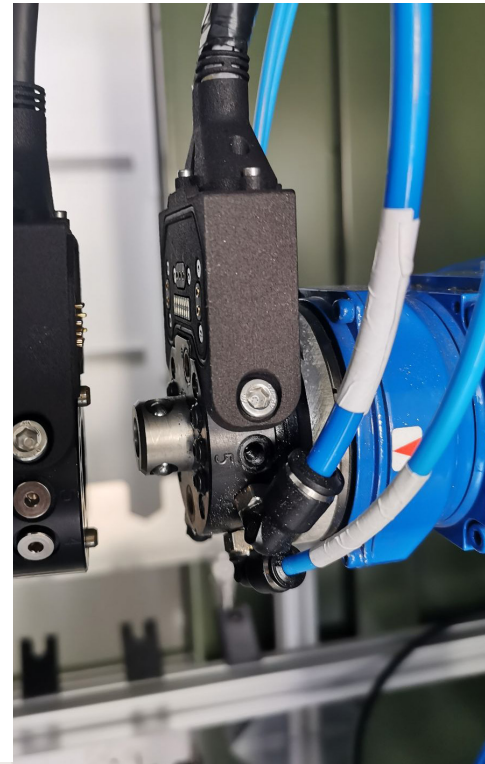
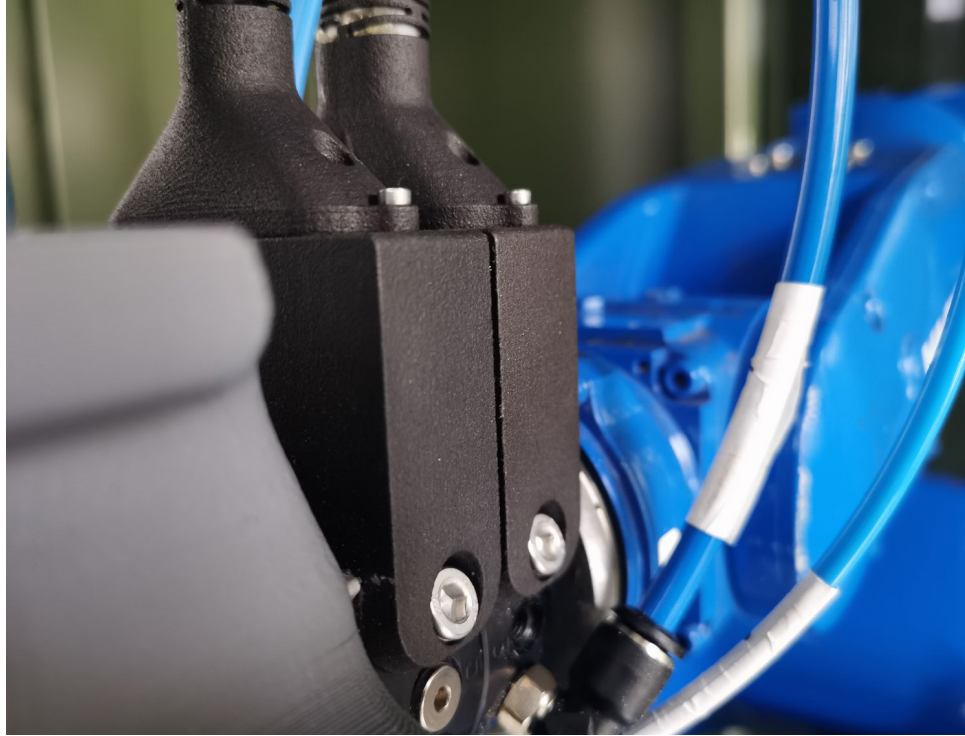
The ability to rapidly iterate a second version with a slightly deeper groove is what makes additive manufacturing hugely valuable over injection molded or machined parts.

David Mason

**Chief Product Officer
at Rivelin Robotics**

The future for Rivelin Robotics

After implementing the connector in all of their robots, the tool changer can now effectively transfer power and data to the connected tool. This streamlines post-processing efforts for metal manufacturing, leading to greater efficiency. Due to the connector's ease of use and precision, it is on the bill of materials for future sales to be used as a production part. With SAF technology, Rivelin Robotics was able to print their own solution which helps shape the future of their robots and company overall.



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